

BLG 354E Signals & Systems

24.05.2021

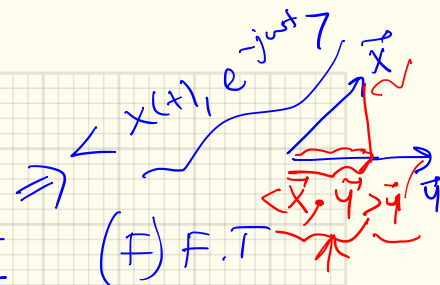
Goode LINAL

Last time

We defined Fourier transform of a signal:

Given $x(t)$:

$$\text{F.T. of } x(t): \underbrace{X(j\omega)} = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$



Given $X(j\omega)$:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega$$

$\langle X(j\omega), e^{j\omega t} \rangle$

We derived F.T. pairs ✓

You can always resort to look-up tables eg. 11.2 in SP First book.
11.3

We were deriving F.T. properties

- 1) Linearity ✓
- 2) Time-shifting

$$\begin{aligned} x(t) &\leftrightarrow X(j\omega) \\ x(t-t_0) &\leftrightarrow e^{-j\omega t_0} X(j\omega) \end{aligned}$$

3) Freq shifting ✓ $x(t) \leftrightarrow X(j\omega)$
 $e^{j\omega_0 t} x(t) \leftrightarrow X(j(\omega - \omega_0))$

4) Time Scaling ✓ $x(at) \leftrightarrow \frac{1}{|a|} X(j(\frac{\omega}{a}))$

7) Convolution Property: $x(t) \leftrightarrow X(j\omega)$
 $y(t) \leftrightarrow Y(j\omega)$

$z(t) = x(t) * y(t) \leftrightarrow Z(j\omega) = ?$

Show

$$Z(j\omega) = \int_{-\infty}^{\infty} z(t) e^{-j\omega t} dt = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x(z) y(t-z) dz e^{-j\omega t} dt$$

(t) integral (z) integral convolution

$$= \int_{-\infty}^{\infty} x(z) \int_{-\infty}^{\infty} y(t-z) e^{-j\omega t} dt dz = \left(\int_{-\infty}^{\infty} x(z) e^{-j\omega z} dz \right) Y(j\omega)$$

(z) (t) $e^{-j\omega z} Y(j\omega)$ (from time shifting property) $X(j\omega)$

$Z(j\omega) = X(j\omega) \cdot Y(j\omega)$ Convolution in Time Domain \Leftrightarrow Multiplication in Frequency Domain

8) Multiplication Property.

$$z(t) = x(t) \cdot y(t) \quad \longleftrightarrow \quad Z(j\omega) = \frac{1}{2\pi} X(j\omega) * Y(j\omega)$$

multiplication in time domain \longleftrightarrow Convolution in Fourier Domain

→ exercise : show this.

9) Differentiation Property:

$$x(t) \longleftrightarrow X(j\omega)$$

$$\frac{d}{dt} x(t) \longleftrightarrow j\omega \cdot X(j\omega)$$

$$\begin{aligned} \text{pf} \rightarrow \frac{d}{dt} (x(t)) &= \frac{d}{dt} \left(\frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \right) \\ &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \underbrace{X(j\omega)} \cdot \underbrace{j\omega}_{\frac{d}{dt} e^{j\omega t}} \cdot e^{j\omega t} d\omega \\ &= \text{F.T.} \left\{ j\omega X(j\omega) \right\} \end{aligned}$$

Generalizes

to :

$$\frac{d^n}{dt^n} x(t) \longleftrightarrow (j\omega)^n X(j\omega)$$

→ show this

→

→ We may be given I/O relationship in an LTI system;
i.t.o. differential equations

$$\begin{array}{ccc}
 x(t) & \xrightarrow{\quad} & \boxed{\text{LTI}} \xrightarrow{\quad} y(t) \\
 X(j\omega) & & H(j\omega) \\
 & & Y(j\omega) = X(j\omega) H(j\omega)
 \end{array}$$

⇒ e.g. $\frac{d^2 y(t)}{dt^2} + 2 \frac{dy(t)}{dt} = \frac{dx(t)}{dt} + 3x(t)$

Take F.T. of both sides:

$$(j\omega)^2 \underline{Y(j\omega)} + 2(j\omega) \underline{Y(j\omega)} = j\omega \underline{X(j\omega)} + 3 \underline{X(j\omega)}$$

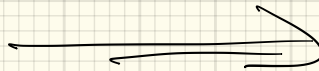
$$Y(j\omega) ((j\omega)^2 + 2j\omega) = X(j\omega) (j\omega + 3)$$

$$\hookrightarrow H(j\omega) = \frac{Y(j\omega)}{X(j\omega)} = \frac{j\omega + 3}{(j\omega)^2 + 2j\omega} = \frac{N(j\omega)}{D(j\omega)}$$

polynomials in $j\omega$

Numerator: polynomial
Corresp. right hand side

Denominator: LHS



In general:

Linear constant
coeff. ODEs:

General

$$\sum_{k=0}^N a_k \frac{d^k}{dt^k} y(t) = \sum_{k=0}^M b_k \frac{d^k}{dt^k} x(t)$$

Take F.T.
of both sides

$$\underbrace{H(j\omega)}_{\substack{\text{Freq response} \\ \downarrow \\ \text{I.F.T.}}} = \frac{\sum_{k=0}^M b_k (j\omega)^k}{\sum_{k=0}^N a_k (j\omega)^k}$$

We can get the $h(t)$: impulse response of the system.

10) If $x(t)$ is real $\Rightarrow X(j\omega)$ is conjugate symmetric:

$X(j\omega)$ (F.T.) is a
complex fn. of ω :

\therefore use to talk about its
polar representation $\&$
(ie. a magnitude $\&$
a phase)
in complex plane \equiv

$$X(-j\omega) = X^*(j\omega)$$

$$X(j\omega) = X^*(-j\omega)$$

even symmetry:

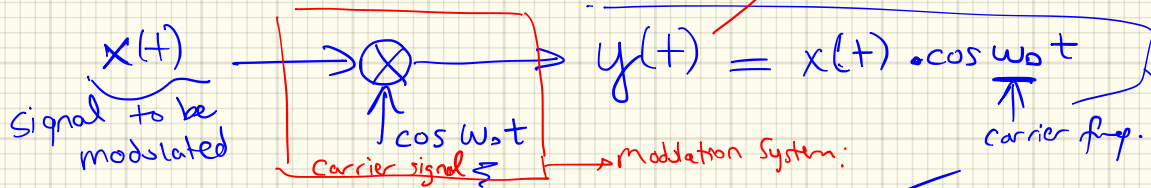
$$\cancel{X}(-j\omega) = -\cancel{X}(j\omega) \quad \text{odd symmetry.}$$

Magnitude
of F.T. \Rightarrow
Phase of
F.T. \Rightarrow

$$X(j\omega) = |X(j\omega)| e^{j\angle X(j\omega)}$$

$$= \text{Re}\{X(j\omega)\} + j \cdot \text{Im}\{X(j\omega)\}$$

11) Modulation Property:



Given Input signal: $x(t) \leftrightarrow X(j\omega)$ ✓

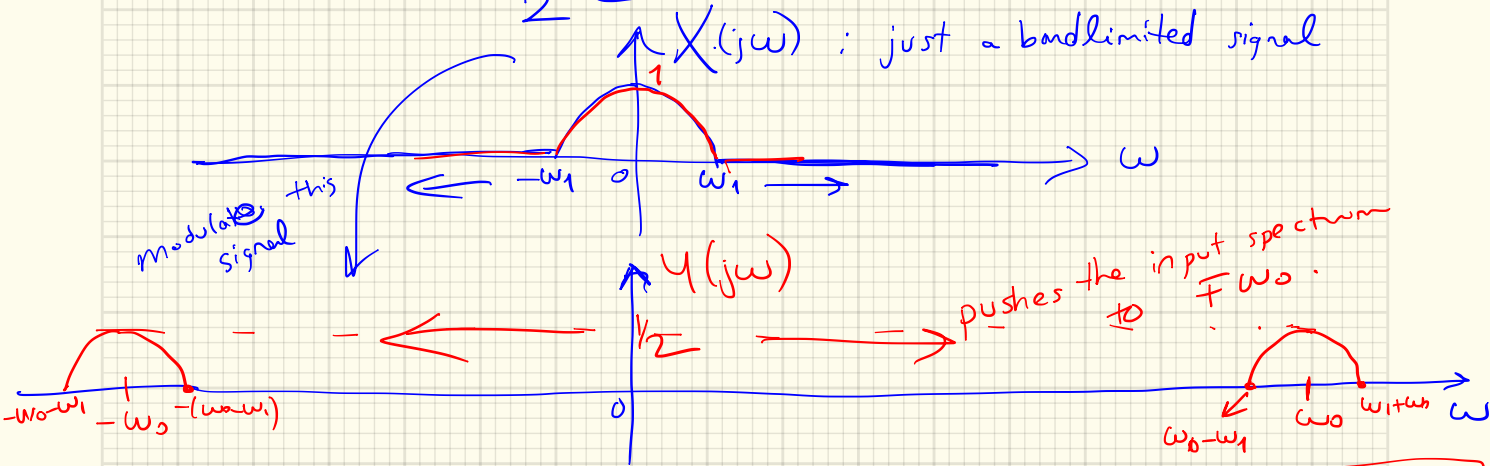
$y(t) \leftrightarrow Y(j\omega) = ?$

Multiplication
in time domain

$$Y(j\omega) = \frac{1}{2\pi} \left[X(j\omega) * \text{F.T}\{\cos \omega_c t\} \right]$$

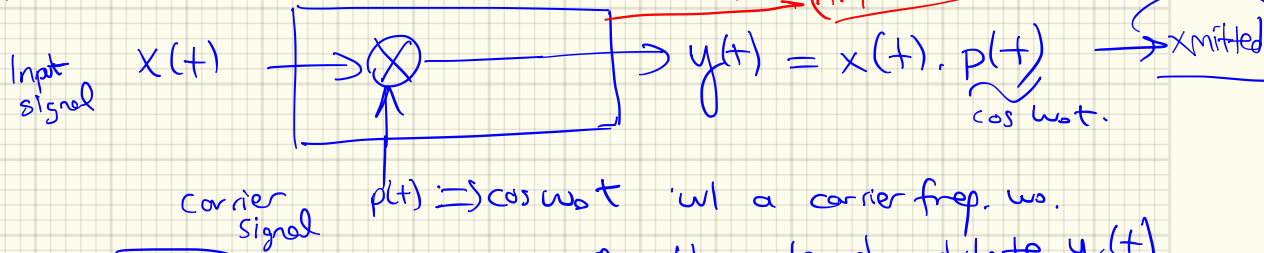
$$\pi \delta(\omega - \omega_c) + \pi \delta(\omega + \omega_c)$$

$$\rightarrow Y(j\omega) = \frac{1}{2} [X(j(\omega - \omega_0)) + X(j(\omega + \omega_0))]]$$



Amplitude Modulation (12.2 SpFirst)

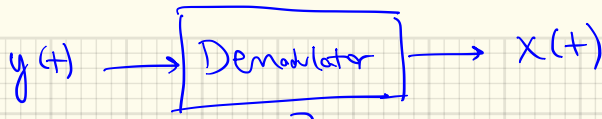
Amplitude Modulation System



Now given $y(t)$ → arrived at the receiver : Q: How to demodulate $y(t)$ to recover $x(t)$ back?

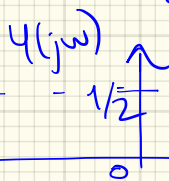
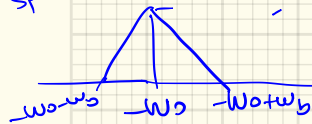
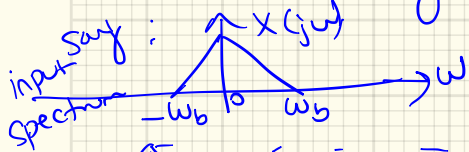
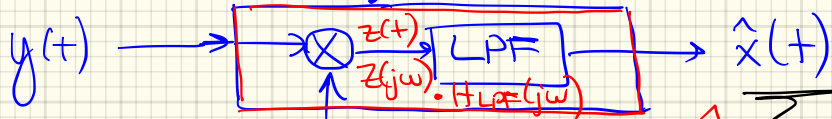
Demodulation

modulated signal



≡ ?

Demodulator System:



$$\hat{X}(j\omega) = Z(j\omega) \cdot H_{LPF}(j\omega)$$

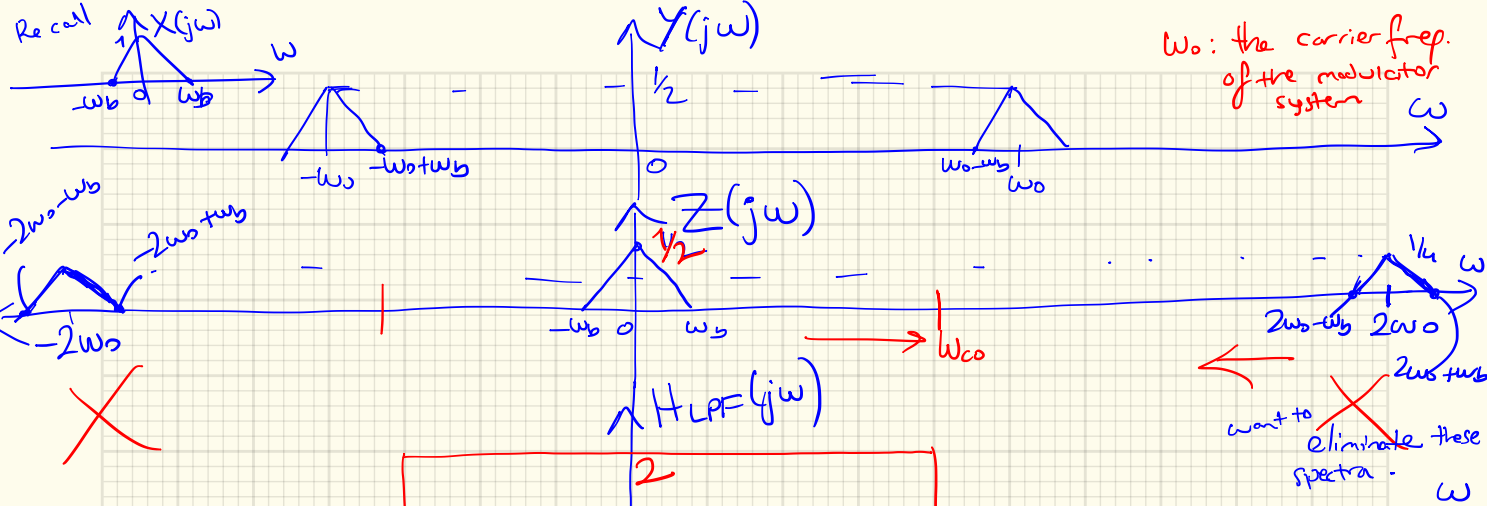
$$z(t) \rightarrow Z(j\omega) = \frac{1}{2} \left[y(j(\omega - \omega_0)) + y(j(\omega + \omega_0)) \right] \quad \text{using multiplication property.}$$

$$Z(j\omega) = \frac{1}{2} \left[\frac{1}{2} X(j(\omega - 2\omega_0)) + \frac{1}{2} X(j\omega) + \frac{1}{2} X(j\omega) + \frac{1}{2} X(j(\omega + 2\omega_0)) \right]$$

$$Z(j\omega) = \frac{1}{2} X(j\omega) + \frac{1}{4} X(j(\omega - 2\omega_0)) + \frac{1}{4} X(j(\omega + 2\omega_0))$$

desired spectrum

extra spectrum components I need to get rid of

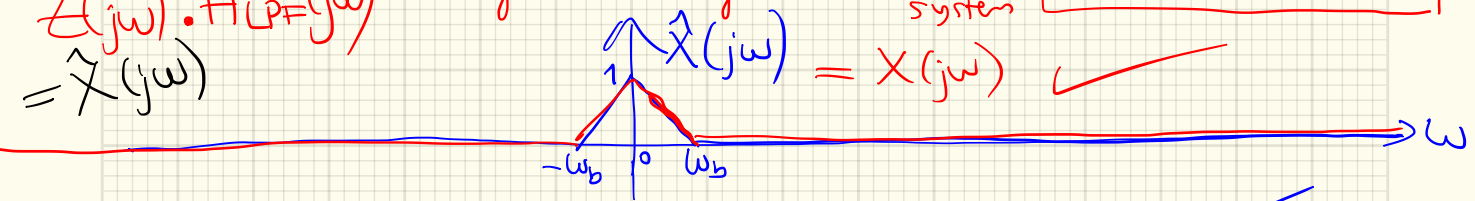


Multiply the two spectra
 $Z(j\omega) \cdot H_{LPF}(j\omega)$
 $= \hat{X}(j\omega)$

ω_{co} : cut-off frequency of the LPF of the Demodulator system

$$\omega_{co} < 2\omega_0 - \omega_b$$

$$\omega_{co} > \omega_b$$



$\rightarrow X(t)$ (ie the modulated & Xmitted signal from the transmitter)

is recovered at the receiver ✓
 This is the idea behind Amplitude modulation.

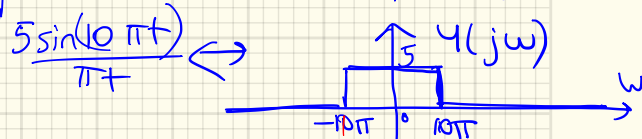
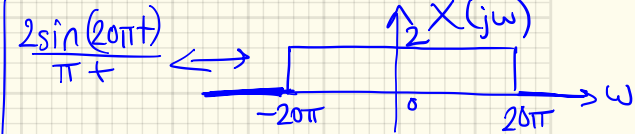
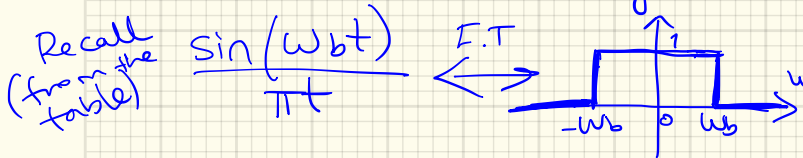
$$H_{LPF}(j\omega) = \begin{cases} 2, & \omega_b < |\omega| < 2\omega_0 - \omega_b \\ 0, & \text{otherwise} \end{cases}$$

$$\hat{X}(j\omega) = H_{LPF}(j\omega) \cdot Z(j\omega) = X(j\omega) \quad \checkmark$$

Now let's do some F.T. taking examples.

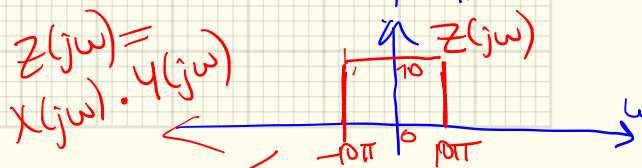
Ex: Given $x(t) = \frac{2 \sin(20\pi t)}{\pi t}$, $y(t) = \frac{5 \sin(10\pi t)}{\pi t}$

Q: Find $z(t) = x(t) * y(t) = \text{F.T.}^{-1} \{ X(j\omega) \cdot Y(j\omega) \}$



$$z(t) = \text{F.T.}^{-1} \{ Z(j\omega) \}$$

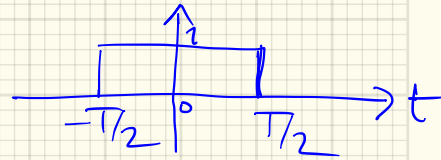
$$z(t) = \frac{10 \sin(10\pi t)}{\pi t}$$



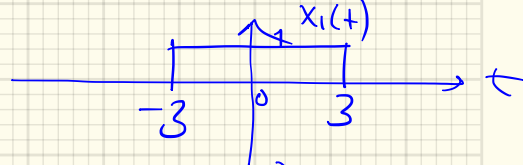
Ex: $X(j\omega) = \frac{2 \sin(3(\omega - 2\pi))}{(\omega - 2\pi)}$ \leftrightarrow F.T⁻¹{.}
 $x(t) = ?$

From Table 11.2

$$\frac{\sin \omega T/2}{\omega/2} \leftrightarrow$$



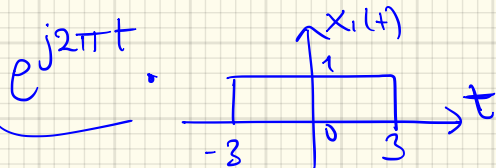
$$\frac{\sin 3\omega}{\omega/2} \leftrightarrow$$



Do a freq. shift

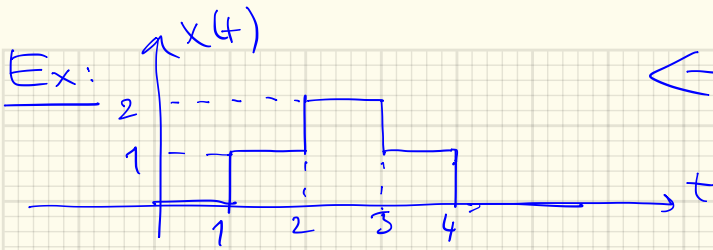
$$e^{j\omega_0 t} x(t) \leftrightarrow X(j(\omega - \omega_0))$$

$$e^{j2\pi t} x_1(t) \leftrightarrow X_1(j(\omega - 2\pi))$$



$$\leftrightarrow \frac{2 \sin(3(\omega - 2\pi))}{(\omega - 2\pi)}$$



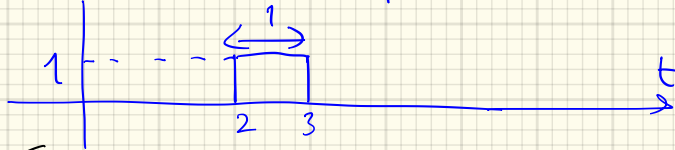
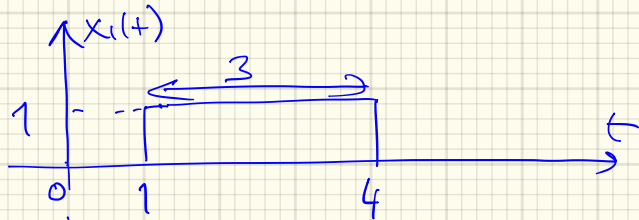


$$\longleftrightarrow X(j\omega) = ?$$

Notice

$$x(t) = x_1(t) + x_2(t)$$

$$X(j\omega) = X_1(j\omega) + X_2(j\omega)$$



exercise:
Calculate the
result
to get:

$$X(j\omega) = e^{-j\omega 5/2} \left(\frac{\sin(3\omega/2)}{\omega/2} + \frac{\sin(\omega/2)}{\omega/2} \right)$$

Ex: $h(t) = 2e^{-2t} u(t) - e^{-t} u(t)$

\uparrow
 $H(j\omega) = ?$

$2 \frac{1}{(2+j\omega)} - \frac{1}{1+j\omega}$ (*)

If we were given

$\hookrightarrow H(j\omega) = \frac{j\omega}{(2+j\omega)(1+j\omega)}$

we should go back to (*) form to take F.T⁻¹?

Partial Fraction Expansion: (PFE)

Given $H(j\omega) = \frac{N(j\omega)}{D(j\omega)} = \frac{j\omega}{(j\omega)^2 + 3j\omega + 2}$ eg. $s^2 + 3s + 2$
 roots $s_{1,2} = -1, -2$

$\frac{j\omega}{(j\omega+2)(j\omega+1)} = \frac{A}{(j\omega+2)} + \frac{B}{(j\omega+1)}$ \rightarrow find A & B.

$\left(\frac{j\omega(j\omega+2)}{(j\omega+2)(j\omega+1)} = \frac{A}{1} + \frac{B \cdot (j\omega+2)}{(j\omega+1)} \right) \Big|_{j\omega=-2}$

$\frac{-2}{-1} = A \rightarrow A = 2$

$$\frac{j\omega \cancel{(j\omega+1)}}{(j\omega+2) \cancel{(j\omega+1)}} = \frac{A \cancel{(j\omega+1)}}{j\omega+2} + B \quad | \quad j\omega = -1$$

$$-\frac{1}{1} = B \rightarrow B = -1$$

$$H(j\omega) = \frac{2}{j\omega+2} - \frac{1}{j\omega+1}$$

$$\rightarrow h(t) = 2e^{-2t}u(t) - e^{-t}u(t)$$

Ex: Given $Y(j\omega) = \frac{1 - \omega^2 + j\omega}{2 - \omega^2 + j3\omega}$ \rightarrow degree of poly num = 2 \rightarrow degree = 2.

* Given $X(j\omega) = \frac{N(j\omega)}{D(j\omega)}$ rational form

If $\deg(N(j\omega)) < \deg(D(j\omega)) \rightarrow$ do PFE as we did in the previous example
 degree " \geq " \rightarrow divide first to get $\deg N < \deg D$

$$\frac{-\omega^2 + j\omega + 1}{-\omega^2 + 3j\omega + 2} \Bigg| \frac{-\omega^2 + 3j\omega + 2}{1}$$

$$-2j\omega - 1$$

$$\rightarrow Y(j\omega) = 1 + \frac{-j2\omega - 1}{(j\omega)^2 + 3j\omega + 2}$$

do PFE

$$\frac{s^2 + 3s + 2}{(s+1)(s+2)}$$

$$\frac{-j2\omega - 1}{(j\omega + 2)(j\omega + 1)} = \frac{A}{j\omega + 2} + \frac{B}{j\omega + 1} \rightarrow \begin{matrix} A = -3 \\ B = 1 \end{matrix}$$

$$Y(j\omega) = 1 - \frac{3}{j\omega + 2} + \frac{1}{j\omega + 1}$$

I.F.T ↓

$$y(t) = \delta(t) - 3e^{-2t}u(t) + e^{-t}u(t)$$

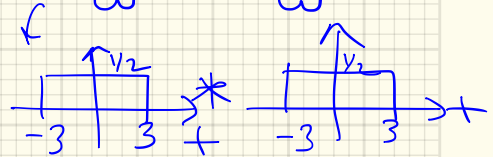
Exercise:

$$H(j\omega) = \frac{\sin^2(3\omega) \cdot \cos(\omega)}{\omega^2} \iff h(t) = ?$$

$$= \underbrace{\cos \omega}_{H_1(j\omega)} \left(\underbrace{\frac{\sin 3\omega}{\omega}}_{H_2(j\omega)} \right)^2$$

$$= \frac{\sin 3\omega}{\omega} \cdot \frac{\sin 3\omega}{\omega}$$

$$h_1(t) = \frac{1}{2}(\delta(t+1) + \delta(t-1))$$



$$h(t) = h_1(t) * h_2(t)$$

$$h(t) = \frac{1}{2}(h_2(t+1) + h_2(t-1))$$



Next: Sampling in Freq. Domain \Rightarrow ^{Go to} Slides

SPFirst -L25, ppt.

(Under Sinif Dosyaları @ Ninova)